

# Embedded Elixir with Nerves and All That Jazz (geddit?)

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<http://cultivatehq.com>



Never start a talk this way





# Cultivate!

(We're hiring)





**Kings Stables Road**

<https://www.youtube.com/watch?v=c8ONmQvN3HI>

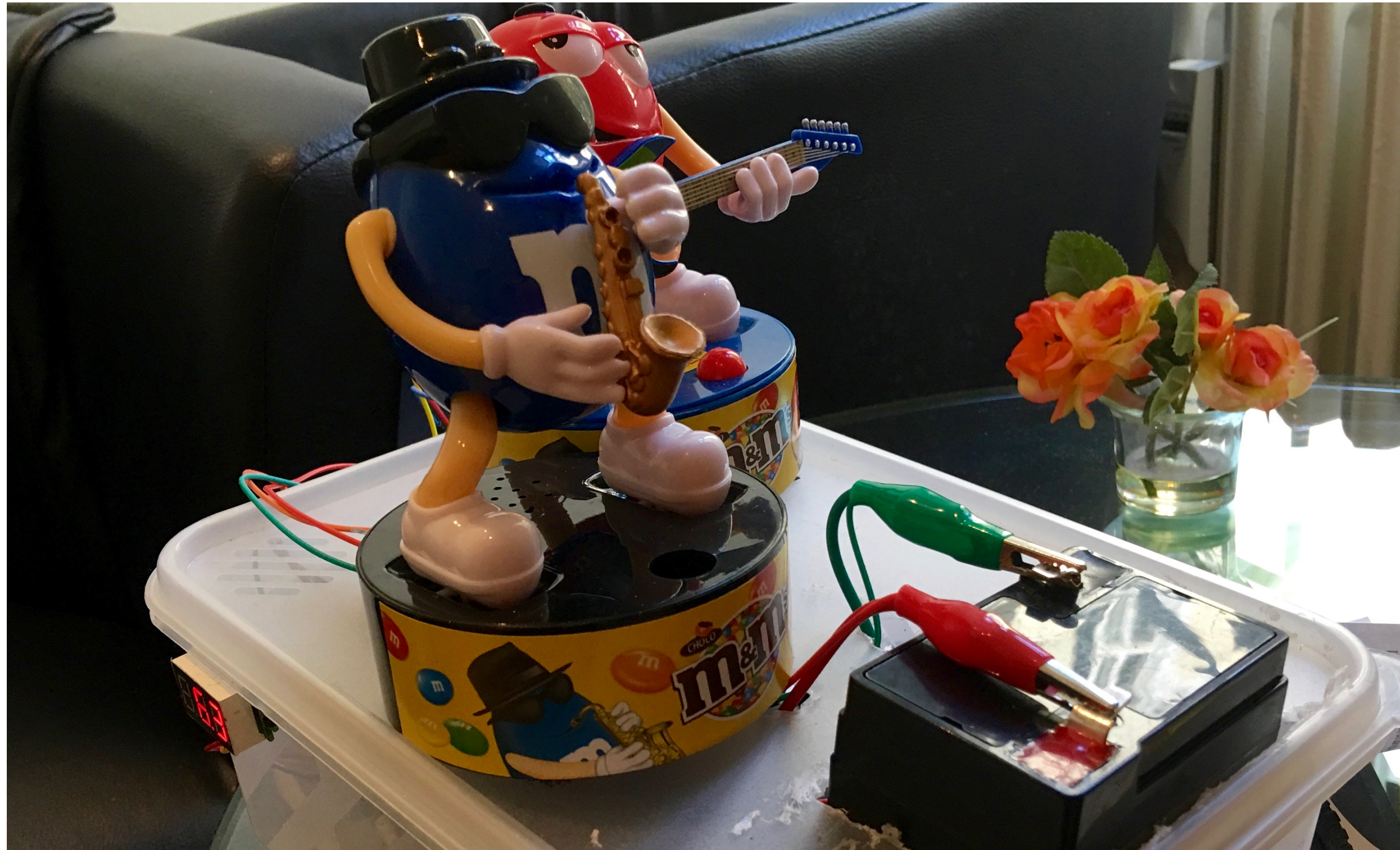












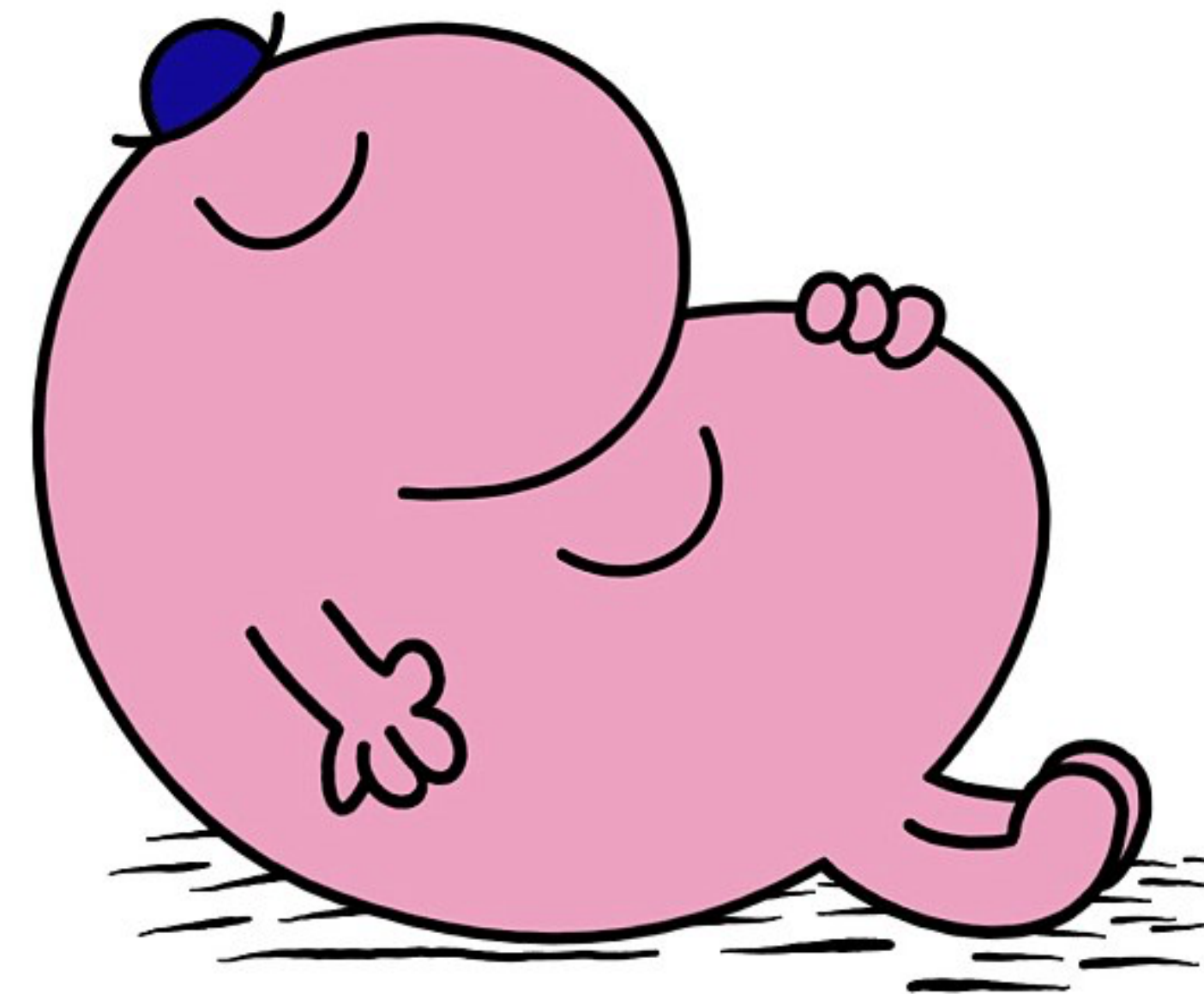
The robot



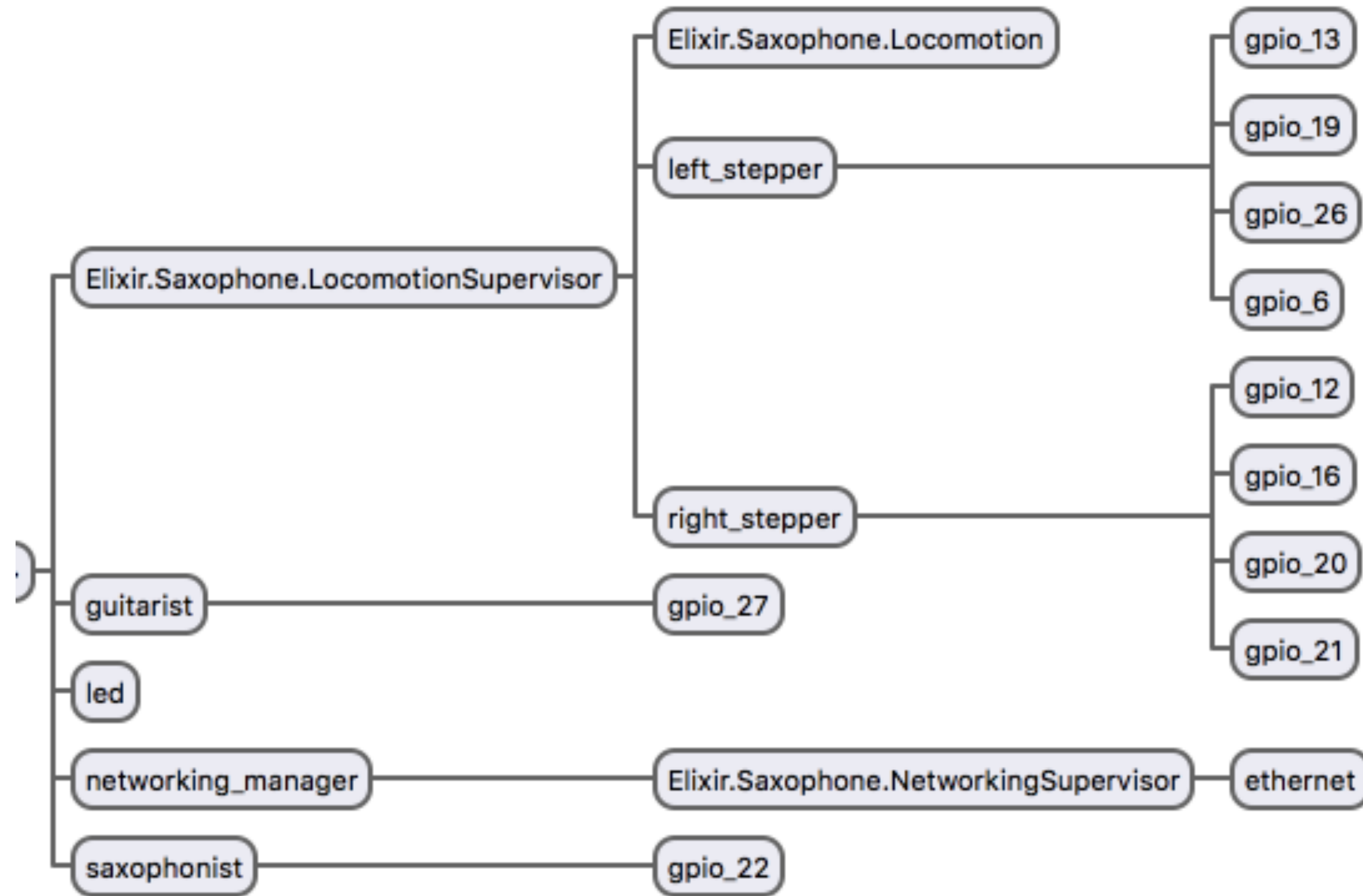
# Why bother?

## **MR. LAZY**

- Fun
- Profit
- Apply OTP



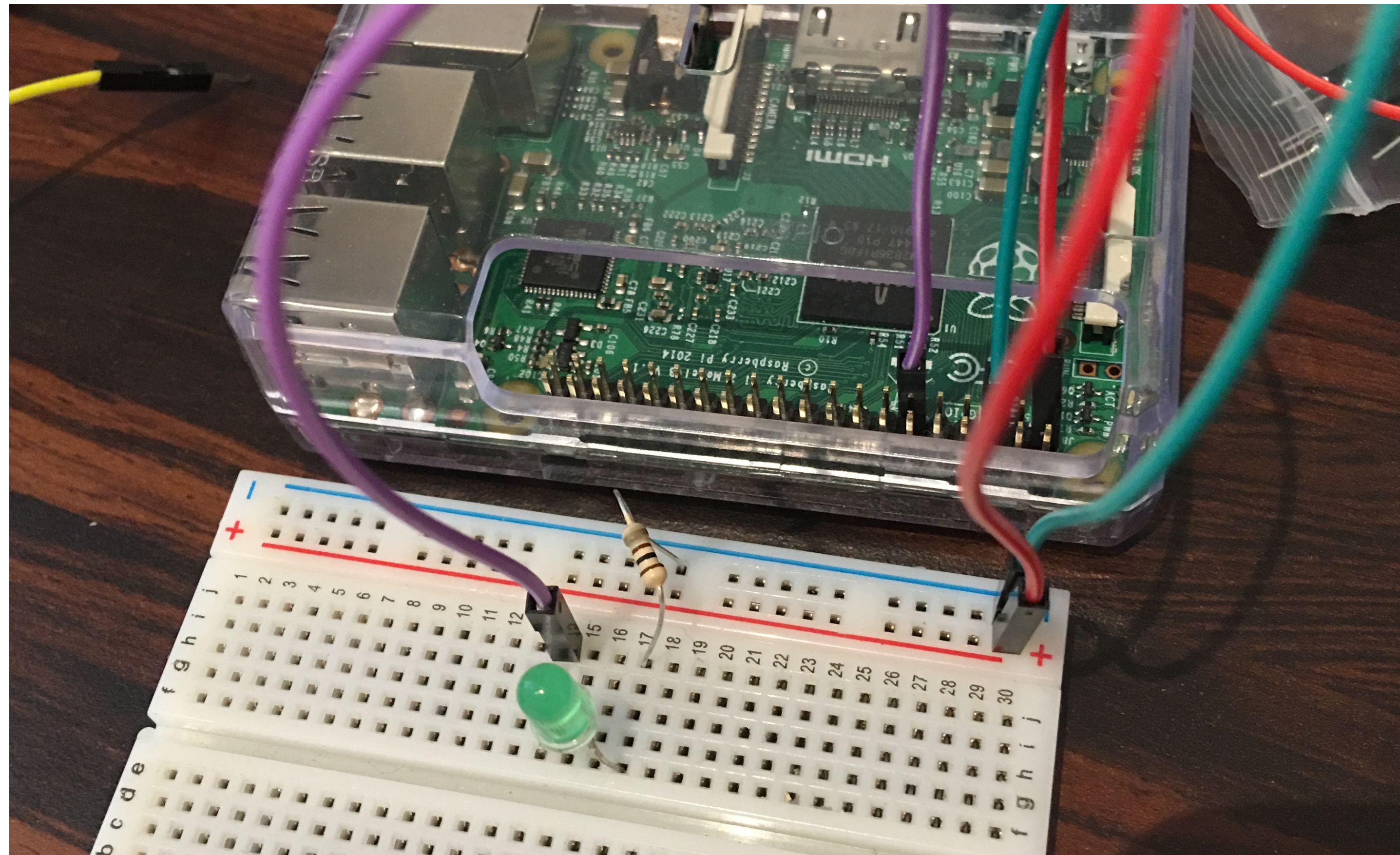




# Supervision Tree

Sax Robot





# Trigger the Sax Player



```
defp deps do
  [
    {:nerves, github: "nerves-project/nerves", branch: "mix"},
    {:elixir_ale, "~> 0.5.0"},
    {:nerves_networking, github: "nerves-project/nerves_networking"}
  ]
end
```

# Elixir Ale (GPIO) & Nerves.Networking

[https://github.com/fhunleth/elixir\\_ale](https://github.com/fhunleth/elixir_ale)



```
[saxophone (master) $ mix test  
==> elixir_ale  
Makefile:17: *** Could not find include directory for ei.h. Chec  
k that Erlang header files are available. Stop.  
could not compile dependency :elixir_ale, "mix compile" failed.  
You can recompile this dependency with "mix deps.compile elixir_  
ale", update it with "mix deps.update elixir_ale" or clean it wi  
th "mix deps.clean elixir_ale"  
** (MatchError) no match of right hand side value: 2  
    mix.exs:4: Mix.Tasks.Compile.ElixirAle.run/1
```

Oh, oh

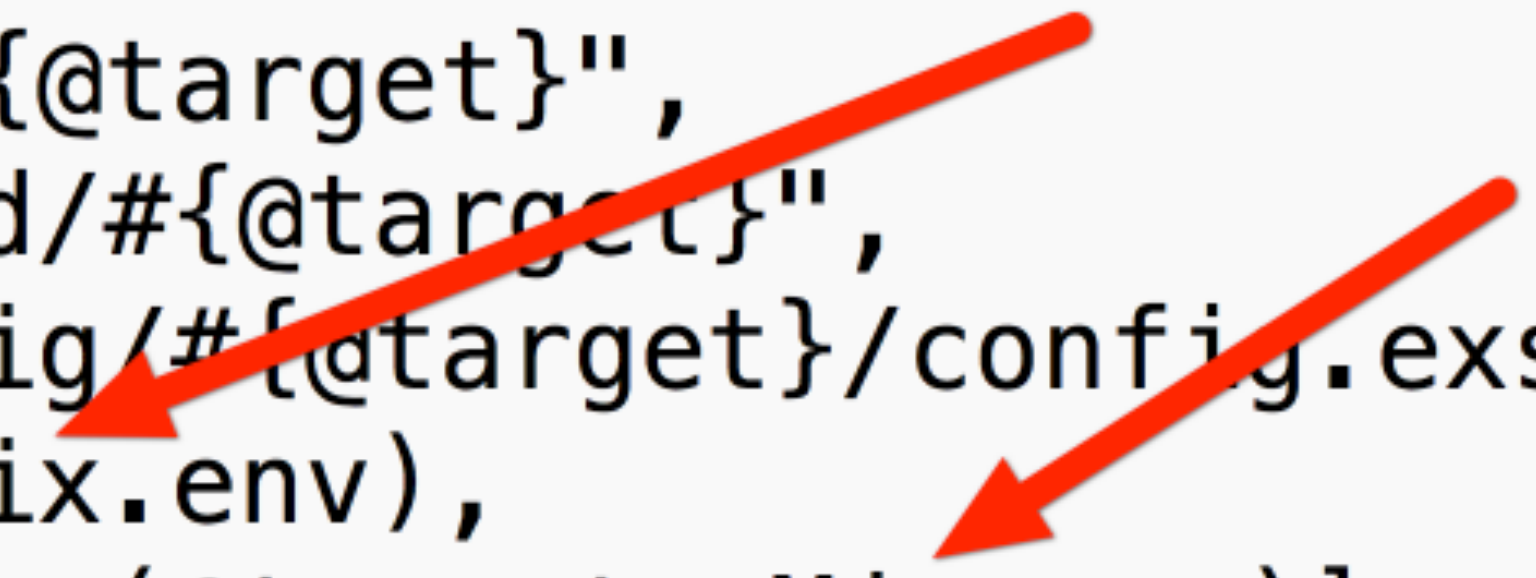


```
{:elixir_ale, "~> 0.5.0", only: [:prod]},  
{:nerves_networking, github: "nerves-project/nerves_networking",  
only: :prod},
```

# Modify mix.exs



```
def project do
  [app: :saxophone,
   version: "0.1.0",
   elixir: "~> 1.2.4",
   archives: [nerves_bootstrap: "~> 0.1"],
   build_embedded: Mix.env == :prod,
   start_permanent: Mix.env == :prod,
   target: @target,
   deps_path: "deps/#{@target}",
   build_path: "_build/#{@target}",
   config_path: "config/#{@target}/config.exs",
   aliases: aliases(Mix.env),
   deps: deps ++ system(@target, Mix.env)]
end
```



# Modify mix.exs



```
def system("rpi2", :prod) do
  [{:nerves_system_rpi2, github: "nerves-proje
end
def system(_, _), do: []

def aliases(:prod) do
  ["deps.precompile": ["nerves.precompile", "c
  "deps.loadpaths": ["deps.loadpaths", "nerv
end
def aliases(_), do: []
```

Modify mix.exs



```
defp applications do
  general_apps = [:logger, :runtime_tools]
  case Mix.env do
    :prod -> [:nerves, :nerves_networking, :elixir_ale | general_apps]
    _ -> general_apps
  end
end
```

# Modify mix.exs



```
if :prod != Mix.env do

  defmodule Nerves.Networking do
    require Logger
    use GenServer

    @moduledoc """
    Does nothing. Stands in for https://github.com/nerves\_io\_ethernet
    during development. Partial implementation for now.
    """
  end
end
```

Fake modules (dev & test)



```
defmodule Gpio do
  use GenServer

  @moduledoc """
  Stand in for Elixir Ale's Gpio in development mode
  """

  defmodule State do
    defstruct pin: 0, direction: nil, pin_states: []
  end

  def start_link(pin, direction, supplied_opts \\ nil) do
    opts = supplied_opts || [name: :gpio #{pin}]
  end
end
```

# Fake objects (dev & test)



```
def write(pid, value) do
  GenServer.call(pid, {:write, value})
end

@doc """
Read the value of the pin. Can be set by #write/1. De
"""
def read(pid) do
  GenServer.call(pid, :read)
end

@doc """
List of the values written to the the pin in order:
the first is the head. Does not include the initial c
"""
def pin_state_log(pid) do
  GenServer.call(pid, :pin_state_log)
end
```

# Extra support for testing



```
use Mix.Config
```

```
config :saxophone, :saxophonist, pin: 4, toggle_time: 0
```

/config/rpi2/test.exs

```
test "play toggles the pin on and off" do
  Saxophonist.play(:saxophonist)
  :timer.sleep(1)
  assert [1, 0] == @gpio |> Gpio.pin_state_log
end
```

/test/saxophonist\_test.exs



```
18 def play(pid) do
19   GenServer.cast(pid, :play)
20 end
21
22 def init({pin, toggle_time}) do
23   {:ok, gpio_pid} = Gpio.start_link(pin, :output)
24   {:ok, %{gpio_pid: gpio_pid, toggle_time: toggle_time}}
25 end
26
27
28 def handle_cast(:play, %{gpio_pid: gpio_pid, toggle_time: toggle_time} = state) do
29   gpio_pid |> Gpio.write(1)
30   :timer.send_after(toggle_time, :turn_off)
31   {:noreply, state}
32 end
33
34 def handle_info(:turn_off, %{gpio_pid: gpio_pid} = status) do
35   gpio_pid |> Gpio.write(0)
36   {:noreply, status}
37 end
38
```

# Saxophonist implementation



```
saxophone (master) $ mix test
```

```
.....
```

```
Finished in 0.4 seconds (0.2s on load, 0.1s on tests)
```

```
26 tests, 0 failures
```

```
Randomized with seed 804014
```

```
saxophone (master) $
```

\O/



```
saxophone (master) $ MIX_ENV=prod mix compile  
Compiled lib/dummies/dummy.ex  
saxophone (master) $ MIX_ENV=prod mix firmware  
Nerves Firmware Assembler  
Building release with MIX_ENV=prod.  
[:nerves, :nerves networking, :elixir ale, :log
```

```
saxophone (master) $ MIX_ENV=prod mix firmware.burn  
Nerves Firmware Burn
```

MIX\_ENV=prod









# Stepper Motor

28BYJ-48 with ULN2003 Driver Board

```
defmodule Saxophone.StepperMotor do
  use GenServer

  defstruct pins: [], direction: :neutral, position: 0,
    step_millis: 10, timer_ref: nil, gear: :low

  @position_pin_values [
    [0, 0, 0, 1],
    [0, 0, 1, 1],
    [0, 0, 1, 0],
    [0, 1, 1, 0],
    [0, 1, 0, 0],
    [1, 1, 0, 0],
    [1, 0, 0, 0],
    [1, 0, 0, 1],
  ]
```

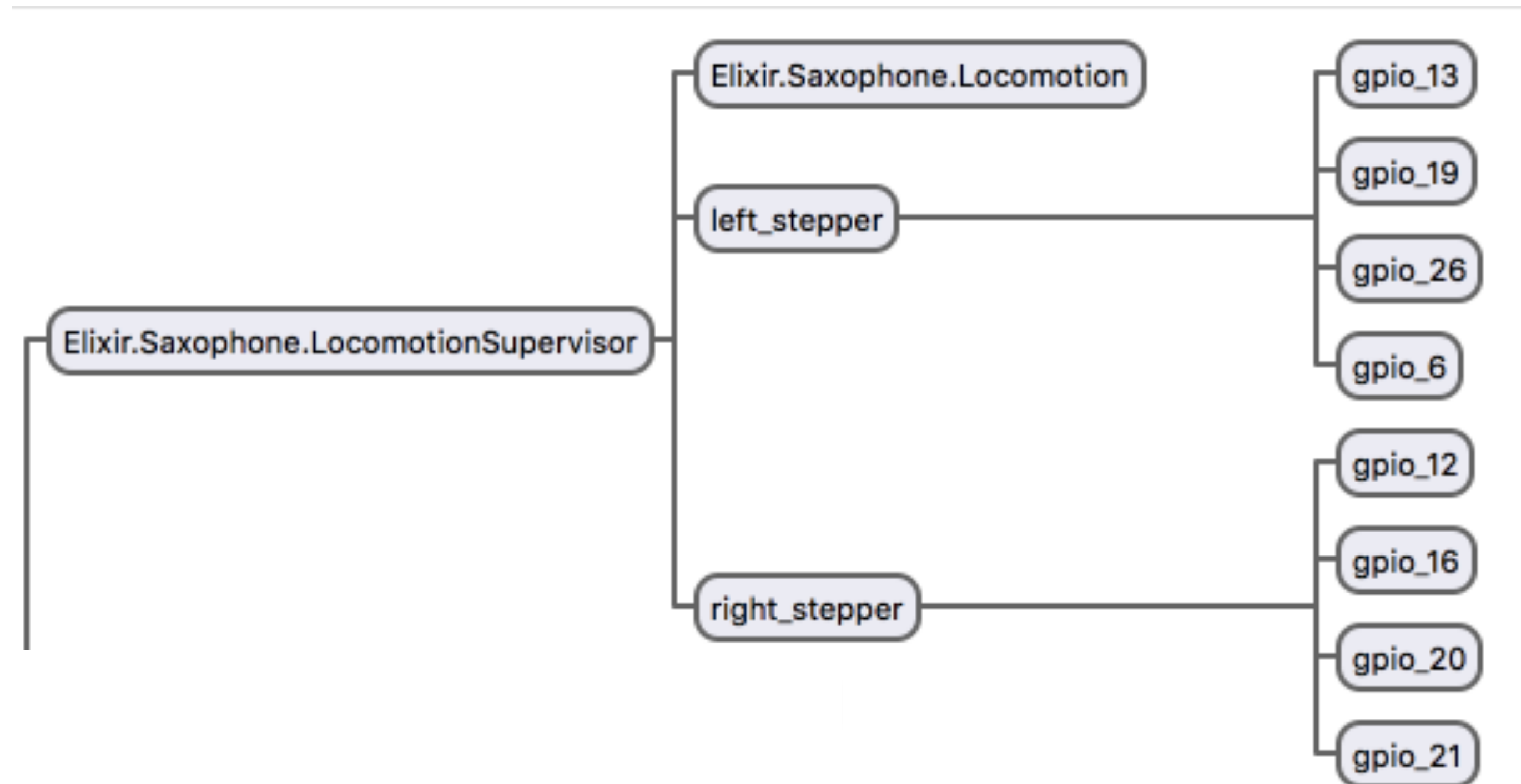
# Stepper motor



```
test "cycling back", %{pid: pid} do
  pid |> StepperMotor.set_direction(:back)
  (7..0) |> Enum.each(fn i ->
    send(pid, :step)
    :timer.sleep(1)
    assert StepperMotor.state(pid).position == i
  end)

  assert Gpio.pin_state_log(:gpio_30) == [0, 0, 0,
    1, 0] |> Enum.reverse
  assert Gpio.pin_state_log(:gpio_33) == [1, 1, 0,
    1, 1] |> Enum.reverse
end
```

One of the motor tests



# Motor supervision





Restart in known good state

```
def init([]) do
  children = [
    worker(Saxophone.StepperMotor, [@stepper_pins[:right]]),
    worker(Saxophone.StepperMotor, [@stepper_pins[:left]]),
    worker(Saxophone.Locomotion, []),
  ]

  supervise(children, strategy: :one_for_all)
end
```

one\_for\_all - known good state



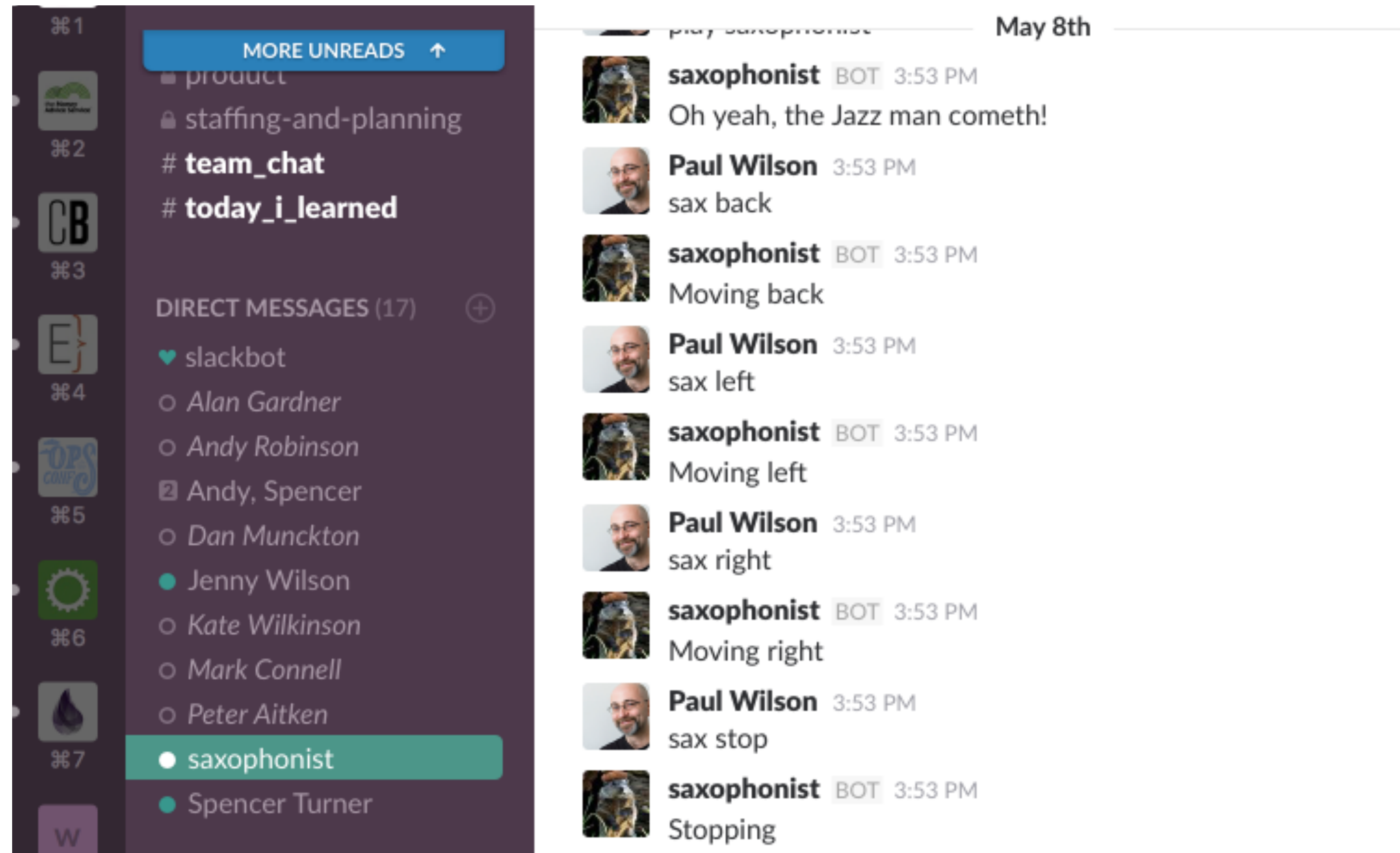
```
defmodule Saxophone.Web.Router do
  use Plug.Router
  plug Plug.Parsers, parsers: [:urlencoded]
  alias Saxophone.{Locomotion, Saxophonist, Web.Html}

  plug :match
  plug :dispatch

  get "/" do
    send_resp(conn, 200, "Hello" |> Html.control_page)
  end

  post "play_sax" do
    :ok = Saxophonist.play(:saxophonist)
    send_resp(conn, 200, "Baker Street, it is not." |>
      Html.control_page)
  end
end
```

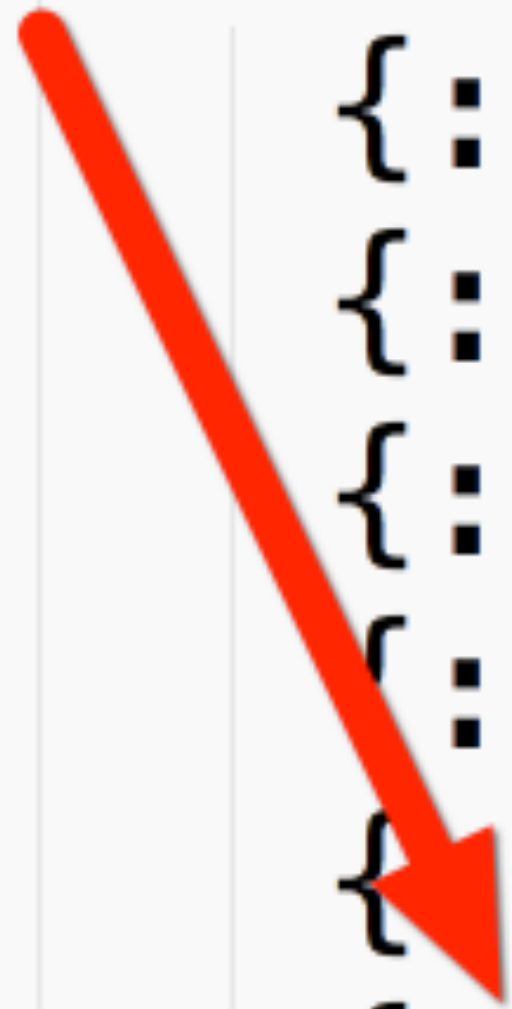
# Web interface



# Slackbot interface



```
defp deps do
  [
    {:nerves, github: "nerves-project/nerves"},
    {:cowboy, "~> 1.0.4"},
    {:plug, "~> 1.1.3"},
    {:elixir_ale, "~> 0.5.0", only: [:plug]},
    {:nerves_networking, github: "nerves-project/nerves_networking"},
    {:websocket_client, github: "jeremyduda/websocket_client"},
    {:slacker, "~> 0.0.2"},
  ]
end
```



# Slacker

<https://github.com/koudelka/slacker>

```
defmodule Saxophone.SlackBot do
  use Slacker
  use Slacker.Matcher

  alias Saxophone.Locomotion

  match ~r/play sax/i, :play_sax
  match ~r/play guitar/i, :play_guitar
  match ~r/^sax (forward|back|left|right|reverse)/i, :move
  match ~r/^sax stop/i, :stop
  match ~r/^sax step\s+(\d+)/i, :step_rate

  def play_sax(_pid, message) do
    say self, message["channel"], "Oh yeah, the Jazz man cometh!"
    Saxophone.Saxophonist.play(:saxophonist)
  end

  def play_guitar(_pid, message) do
```

# Slackbot code



```
saxophone — beam.smp -- -root /usr/local/Cellar/erlang/18.3/lib/erlang -prognose erl -- -home ~ -- -pa /usr/local/Cellar/elixir/1.2.4/bin/./lib/eex/ebin /usr/local/Cellar/elixir/1.2.4/bin/./lib/elixir/ebin /usr/local/Cellar/elixir/1.2.4/bin/./lib/otp/ebin
iex(saxophone@192.168.22.5)14> {:ok, slack} = Saxophone.SlackBot.start_link(token)
```

Let's try it!





The 1970s



```
saxophone — -bash — 68x17
^Csaxophone (testing) $ iex --name bob --cookie saxophone --remsh sa
phone@192.168.22.5
```

ntpd to the rescue







```

45 def init(_) do
46   send(self, :sync_the_time)
47   {:ok, %Saxophone.Ntp{}}
48 end
49
50 def handle_info(:sync_the_time, state) do
51   success = do_sync
52   schedule_next_sync(success)
53
54   {:noreply, %{state | time_set: success}}
55 end
56
57 def handle_call(:time_set?, _from, state = %{time_set: time_set}) do
58   {:reply, time_set, state}
59 end
60
61 defp schedule_next_sync(last_sync_successful) do
62   Process.send_after(self, :sync_the_time, next_sync_time(last_sync_successful))
63 end
64
65 defp do_sync do
66   case Porcelain.shell(@command) do
67     %Result{status: 0} ->
68       Logger.info "Successfully set the time over with NTP"
69       true
70     %Result{out: out, status: status} ->
71       Logger.error "Failed to set the time with NTP:\n#{out}\n#{status |> inspect}"
72       false
73   end
74 end
75
76 defp next_sync_time(_last_sync_successful = true), do: :timer.minutes(30)
77 defp next_sync_time(_last_sync_successful = false), do: :timer.seconds(10)

```



```
[ 3.249422] usb 1-1.4: New USB device found, idVendor=1c4f, idProduct=0026
[ 3.261366] usb 1-1.4: New USB device strings: Mfr=1, Product=2, SerialNum=
[ 3.279776] usb 1-1.4: Product: USB Keyboard
[ 3.287816] usb 1-1.4: Manufacturer: SIGMACHIP
[ 3.307131] input: SIGMACHIP USB Keyboard as /devices/platform/soc/3f980000.
[ 3.377354] hid-generic 0003:1C4F:0026.0001: input,hidraw0: USB HID v1.10 Ke
[ 3.405172] input: SIGMACHIP USB Keyboard as /devices/platform/soc/3f980000.
[ 3.477302] hid-generic 0003:1C4F:0026.0002: input,hidraw1: USB HID v1.10 De
Erlang/OTP 18 [erts-7.2.1] [source] [smp:4:4] [async-threads:10] [kernel-poll:f

00:00:06.255 [debug] Elixir.Nerves.Networking Starting

00:00:06.282 [debug] initializing Networking.Subsystem
Interactive Elixir (1.2.4) - press Ctrl+C to exit (type h() ENTER for help)
iex(saxophone@192.168.22.5)1> [ 10.381447] random: nonblocking pool is initial

nil
iex(saxophone@192.168.22.5)2> HTTPoison.get "google.com"
```

# HTTPoison gotcha



```
[ 3.269731] usb 1-1.4: Product: USB Keyboard
[ 3.277746] usb 1-1.4: Manufacturer: SIGMACHIP
[ 3.297208] input: SIGMACHIP USB Keyboard as /devices/platform/soc/3f980000
[ 3.367404] hid-generic 0003:1C4F:0026.0001: input,hidraw0: USB HID v1.10 K
[ 3.395275] input: SIGMACHIP USB Keyboard as /devices/platform/soc/3f980000
[ 3.467369] hid-generic 0003:1C4F:0026.0002: input,hidraw1: USB HID v1.10 De
Erlang/OTP 18 [erts-7.2.1] [source] [smp:4:4] [async-threads:10] [kernel-poll:]

00:00:06.202 [debug] Elixir.Nerves.Networking Starting

00:00:06.227 [debug] initializing Networking.Subsystem
Interactive Elixir (1.2.4) - press Ctrl+C to exit (type h() ENTER for help)
iex(saxophone@192.168.22.5)1> [ 10.501424] random: nonblocking pool is initial

nil
iex(saxophone@192.168.22.5)2>
nil
iex(saxophone@192.168.22.5)3> Nerves.Networking.setup :eth0_
```

# HTTTPoison ok



**nerves**  
members | <http://nerves-project.org> and <http://bakeware.io>

Yesterday

Reconnecting in 270 seconds... Retry now

joined #nerves. Also, @marceldegraaf joined.

**paulwilson** 4:35 PM  
@fhunleth: if one of the usb dongles supported is Ralink I can give it a go. I've a Ralink RT5

**fhunleth** 4:41 PM  
So close. Here's the Ralink list: <https://wireless.wiki.kernel.org/en/users/drivers/rt2800usb>  
uses?

I'm sure that I could enable your driver. I think that I'll need some @jschneck to be able to completely converted to the new `mix` build process.

**jschneck** 4:47 PM  
Sure, let me know what you need added and I'll bump it

# Slack connectivity





# Ariane 5 Maiden Flight

Flight 501 - 4 June 1996

# Ariane 5 Failure

- Software error in the Inertial Reference System
- 64 bit to 16 bit caused overflow
- Subsystem crashed entire navigation system
- (Not even needed after takeoff)



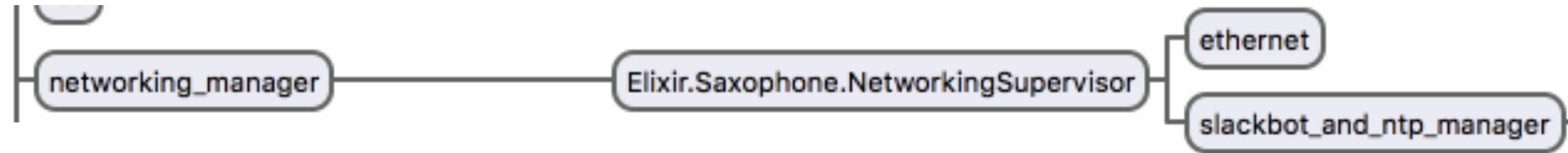
# Supervision tree considerations

- Ethernet may fail to come up, but we want it to keep trying
- The SlackBot cannot be allowed to try and connect until there is a network connection
- There's no point in connecting to Slack until we've set the time
- SlackBot failure, even continuous, should not bring down the entire application. Just keep retrying.

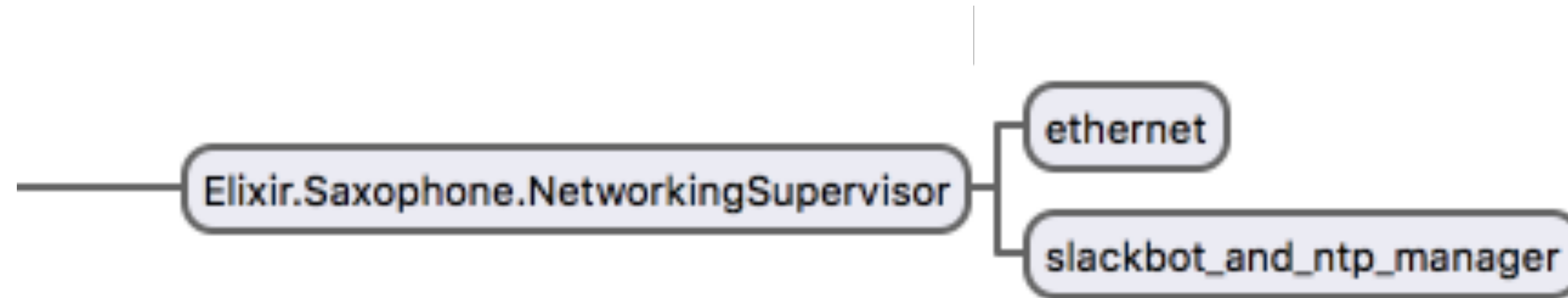


```
def init([]) do
  children = [
    worker(Saxophone.Web.Router, []),
    worker(Gpio, [@led_pin, :output, [name: :led]]),
    worker(Saxophone.Saxophonist, [@sax_pin, @sax_toggle_time, [name: :saxophonist]], id: :s),
    worker(Saxophone.Saxophonist, [@guitar_pin, @guitar_toggle_time, [name: :guitarist]], id: :g),
    supervisor(Saxophone.LocomotionSupervisor, []),
    worker(Saxophone.GenServerRestarter, [Saxophone.NetworkingSupervisor, :start_link, [],
      @ethernet_retry_time, [name: :networking_manager]]),
  ]
  supervise(children, strategy: :one_for_one)
end
```





```
1 defmodule Saxophone.GenServerRestarter do
2   use GenServer
3
4   def start_link(module, function, args, retry_interval, restarter_otp_opts \\ [], start_
5     GenServer.start_link(__MODULE__,
6       {%{retry_interval: retry_interval,
7         module: module,
8         function: function,
9         args: args}, start_delay},
10      restarter_otp_opts)
11 end
12
13 def init({status, start_delay}) do
14   Process.send_after(self, :start, start_delay)
15   Process.flag(:trap_exit, true)
16   {:ok, status}
17 end
18
19 def handle_info(:start, state = %{module: module, function: function, args: args}) do
20   {:ok, pid} = apply(module, function, args)
21   Process.link(pid)
22   {:noreply, state}
23 end
24
25 def handle_info({:EXIT, _pid, _reason}, status = %{retry_interval: retry_interval}) do
26   Process.send_after(self, :start, retry_interval)
27   {:noreply, status}
28 end
29 end
```



```
1 defmodule Saxophone.NetworkingSupervisor do
2   use Supervisor
3
4   @ethernet_opts Application.get_env(:saxophone, :ethernet_opts) || []
5
6   @slackbot_retry_time Application.get_env(:saxophone, :slackbot_retry_seconds) |> :timer.seconds
7   @slackbot_start_delay Application.get_env(:saxophone, :slackbot_start_delay_seconds) |> :timer.seconds
8
9   def start_link do
10    Supervisor.start_link(__MODULE__, [], name: __MODULE__)
11  end
12
13  def init(_) do
14    children = [
15      worker(Nerves.Networking, [:eth0, @ethernet_opts], function: :setup),
16      worker(Saxophone.GenServerRestarter, [Saxophone.SlackWithNtpSupervisor,
17      :start_link,
18      [],
19      @slackbot_retry_time,
20      [name: :slackbot_and_ntp_manager],
21      @slackbot_start_delay])
22    ]
23
24    supervise(children, strategy: :rest_for_one)
25  end
26 end
```





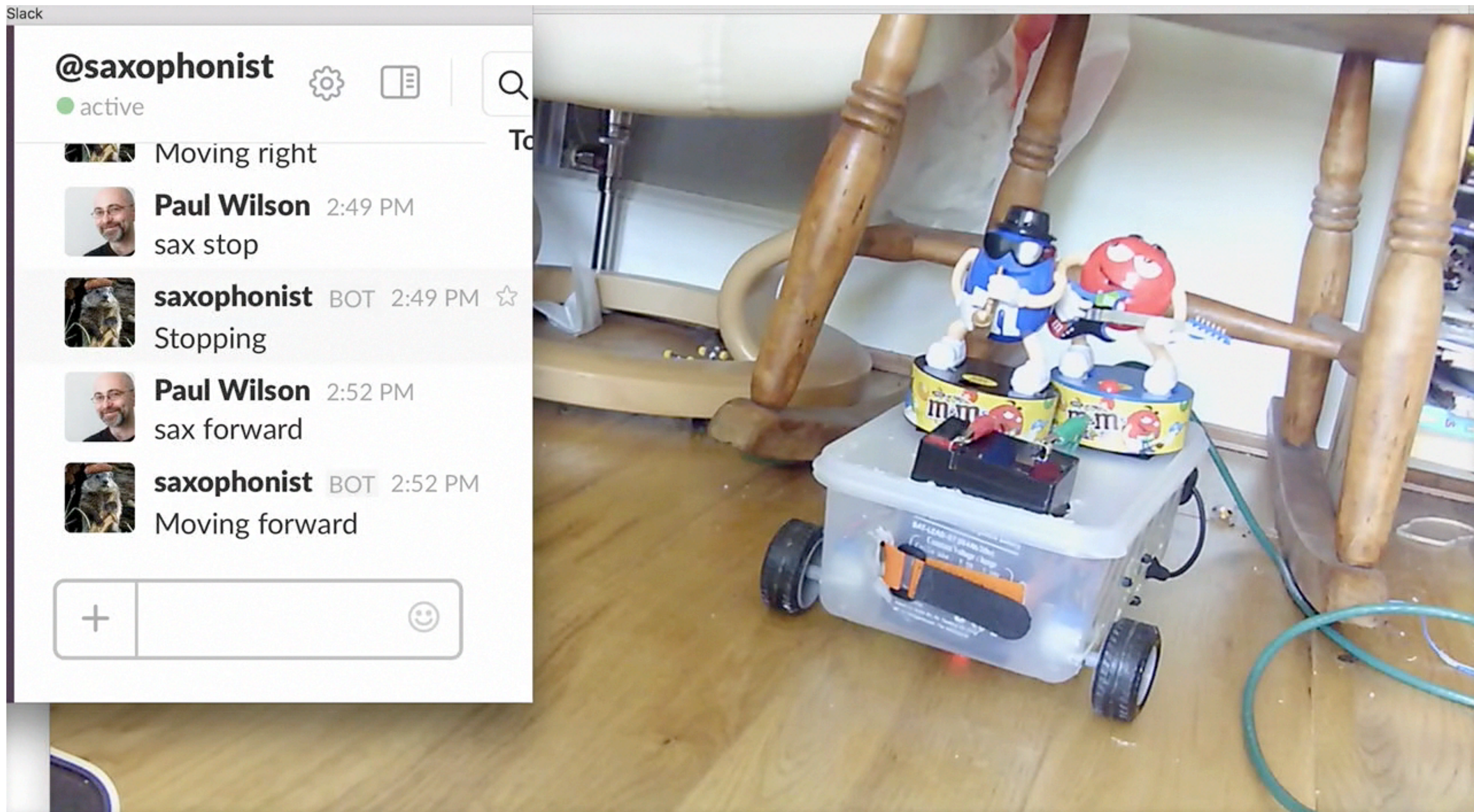
```
## Callbacks
def init(_) do
  true = do_sync
  schedule_next_sync(true)
  {:ok, %Saxophone.Ntp{}}
end
```

Elixir.Saxophone.Ntp



```
1 defmodule Saxophone.SlackWithNtpSupervisor do
2   use Supervisor
3
4   @slackbot_token Application.get_env(:saxophone, :slackbot_token)
5
6   def start_link do
7     Supervisor.start_link(__MODULE__, [], name: __MODULE__)
8   end
9
10  def init(_) do
11    children = [
12      worker(Saxophone.Ntp, []),
13      worker(Saxophone.SlackBot, [@slackbot_token, [name: :slackbot]]),
14    ]
15
16    supervise(children, strategy: :rest_for_one)
17  end
18 end
19
```

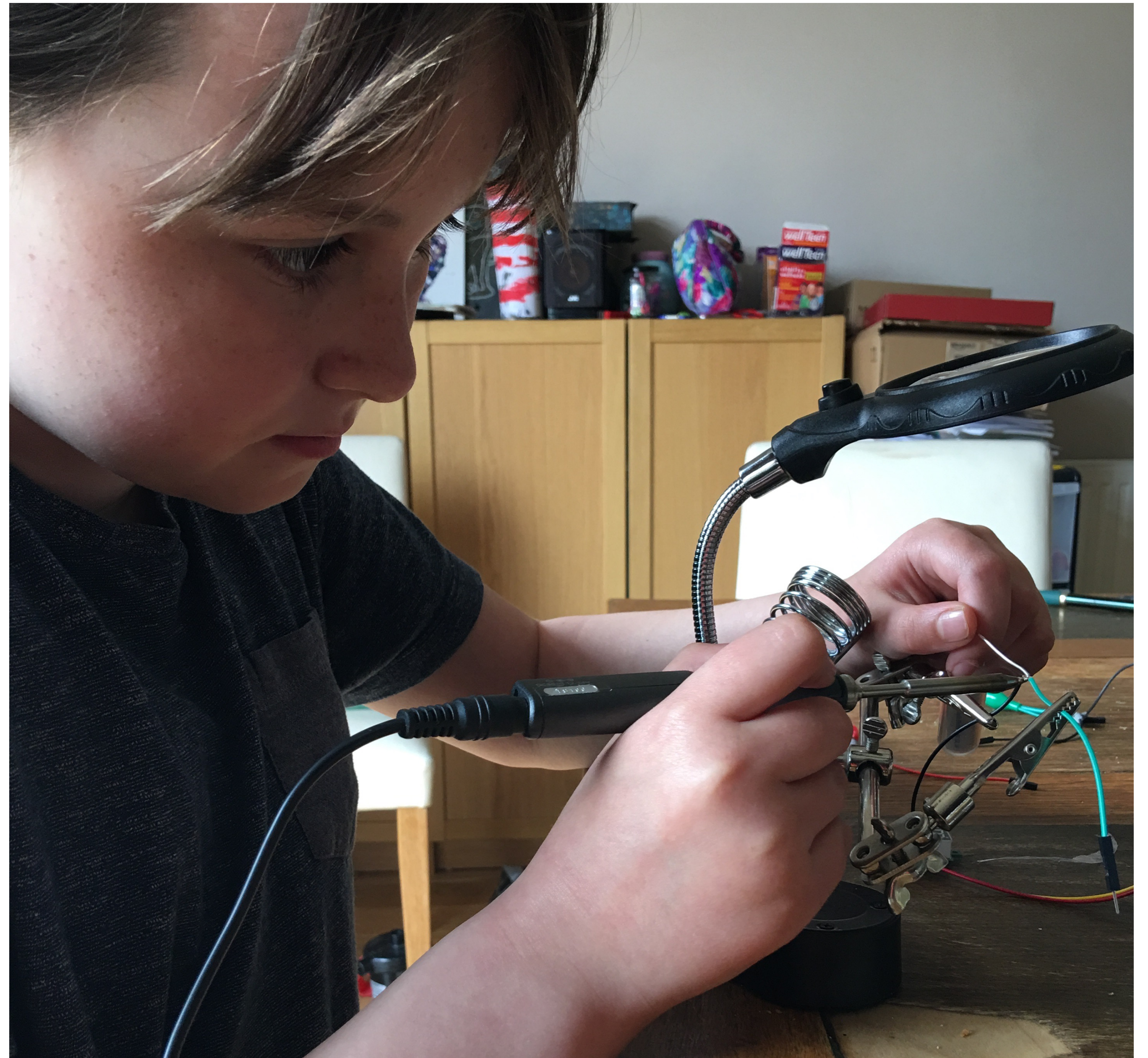




# Slack bot



# Outsourcing the soldering





# More information

- Justin Schneck's keynote at Elixir Conf EU 2016, about an hour ago. Remember?
- <http://nerves-project.org>
- <https://github.com/nerves-project>
- <https://github.com/paulanthonywilson/saxophone>
- Wendy Smoak's Cat Feeder <http://wsmoak.net/2016/04/03/cat-feeder-fabrication.html>
- Nerves channel on Elixir Slack <https://elixir-lang.slack.com/archives/nerves>
- <http://www.cultivatehq.com/posts/> (soon)